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The social coevolution hypothesis for the origin of enzymatic cooperation

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Supplementary Material for “The social coevolution hypothesis for the origin of enzymatic cooperation”

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S1 The Model

1 We need a total of seven equations to capture the ecological dynamics of both the
2 residents and the mutants. From the life cycle in figure one and the description
3 in the main text, this allows us to write (for the residents):

$$\begin{aligned}
 \frac{d[X]}{dt} &= (((r_X (1 - d) \eta) - \mu_X) [X]) \\
 &\quad - (\beta (1 + \zeta c) [X][Y]) \\
 &\quad + (((1 + \kappa) (1 - d) r_X \eta) + \mu_Y + (1 - \xi c) \delta) [XY] \\
 \frac{d[Y]}{dt} &= (((r_Y (1 - c) \eta) - \mu_Y) [Y]) \\
 &\quad - (\beta (1 + \zeta c) [Y][X]) \\
 &\quad + (((1 + \kappa) r_Y (1 - c) (1 + \omega d) \eta) + \mu_X + (1 - \xi c) \delta) [XY] \\
 \frac{d[XY]}{dt} &= \beta (1 + \zeta c) [Y][X] \\
 &\quad - (\mu_Y + \mu_X + (1 - \xi c) \delta - ((1 + \lambda d) (1 + \alpha c)) r_{XY} \eta) [XY]
 \end{aligned} \tag{S.1}$$

4 Where $\eta = 1 - k([T] = [X] + [XY] + [Y])$ is density dependent regulation, and
5 k controls its extent.

6 Following the standard adaptive dynamics approach, we assume that invad-
7 ing mutants are rare enough so as not to affect the dynamics of the resident
8 population (Metz et al., 1992; Rand et al., 1994; Dieckmann and Law, 1996).
9 Accordingly, we only need four additional equations to capture the dynamics of
10 mutants in each gene (X' and Y'), which are expressions for $\frac{d[X']}{dt}$, $\frac{d[Y']}{dt}$, $\frac{d[X'Y']}{dt}$,

11 and $\frac{d[X'Y']}{dt}$. These differ from system S.1 only in their values for c and d , the
 12 mutant trait values, which we denote with primes as c' and d' .

13 The equations for the mutant can be written in the form (Van Baalen and
 14 Jansen, 2001):

$$\frac{d[i']}{dt} = F'_i[i'] - \beta'[i'][\bar{j}] + P'_i[i'j] \quad (\text{S.2})$$

$$\frac{d[i'j]}{dt} = \beta'[i'][\bar{j}] - M'_{ij}[i'j] \quad (\text{S.3})$$

15 Where $F_i = (\rho_i - \mu_i)$ is the growth of i alone, $P_i = (\mu_j + \theta_i + \delta)$ is the
 16 production of i 's from complexes, and $M_{ij} = (\mu_i + \mu_j + \delta - \rho_{ij})$ is the loss of
 17 complexes. The primes indicate mutant values in gene i , and $[\bar{j}]$ is the equilib-
 18 rium frequency of copies produced in the absence of the mutant. This form for
 19 an invasion condition was first identified by Van Baalen and Jansen (2001). For
 20 illustration, we reproduce each term for replicator Y , but equivalent equations
 21 can be extracted for replicator X .

$$F'_Y = (r_Y (1 - c') ((1 - k([T]))) - \mu_Y \quad (\text{S.4})$$

$$P'_Y = ((1 + \kappa) r_Y (1 - c') (1 + \omega d) ((1 - k([T]))) + \mu_X + (1 - \xi c') \delta)$$

$$M'_{XY} = (\mu_Y + \mu_X + (1 - \xi c') \delta - ((1 + \lambda d) (1 + \alpha c')) r_{XY} ((1 - k([T])))$$

$$\beta_Y = \beta (1 + \zeta c')$$

22 We can rewrite system S.4 in matrix form as:

$$\frac{d}{dt} \begin{bmatrix} [i'] \\ [i'j] \end{bmatrix} = \begin{bmatrix} F'_i - \beta'[\bar{j}] & P'_i \\ \beta'[\bar{j}] & -M'_{ij} \end{bmatrix} \begin{bmatrix} [i'] \\ [i'j] \end{bmatrix} \quad (\text{S.5})$$

23 The first matrix on the right hand side of equation S.5 contains all the
 24 information we need to determine the spread of a rare mutant (Van Baalen and
 25 Jansen, 2001; Hurford et al., 2009). A useful decomposition of this matrix is
 26 the form $\mathbf{F}_i - \mathbf{V}_i$, where,

$$\mathbf{F}_i = \begin{bmatrix} F'_i & P'_i \\ 0 & 0 \end{bmatrix}, \mathbf{V}_i = \begin{bmatrix} \beta'[\bar{j}] & 0 \\ -\beta'[\bar{j}] & M'_{ij} \end{bmatrix} \quad (\text{S.6})$$

27 According to the next generation theorem (Hurford et al., 2009), given that
 28 $\mathbf{F} > 0$, \mathbf{V}^{-1} , and the spectral bound of $-\mathbf{V}$ is negative, the condition for a
 29 mutant to invade is that the spectral radius of $\mathbf{FV}^{-1} > 1$. This condition can
 30 be written as:

$$\frac{P'_i}{M'_{ij}} + \frac{F'_i}{\beta'[\bar{j}]} > 1 \quad (\text{S.7})$$

31 This is equation 2 in the main text.

32 Taking the derivatives of equation S.7 with respect to small changes in mu-
33 tant trait values gives the direction of selection in each trait, which we use to
34 produce Figure 2c.

35 Coevolution is driven by the interaction between the two mutant trait values,
36 c' and d' . These interaction terms are contained entirely in the derivative of
37 the first term of Equation (S.7, and it can easily be seen that $\frac{\partial}{\partial c'} \left(\frac{P'_i}{M'_{ij}} \right)$ and
38 $\frac{\partial}{\partial d'} \left(\frac{P'_i}{M'_{ij}} \right)$ are positive functions of c' and d' , respectively.

39 This is not a quantitative model, and therefore we do not extensively dis-
40 cuss the specific values the parameters can take. Those with a specific chemical
41 system in mind should use parameter values relevant to the biochemistry of the
42 molecules at hand. Here, we simply point out that what matters for the evolu-
43 tion of cooperation is the ratio of different key parameters, found in equation
44 (S.7). For example, if the baseline replication rate, r_i , is of several orders smaller
45 than the baseline association rate, β , and the benefit to cooperation, ω , is small
46 relative the other parameters, it will be difficult for cooperation to spread. This
47 is because in the absence of an association mutation, individuals often already
48 find themselves in pairs, and the additional benefit of cooperation is insignifi-
49 cant. All the important relationships can be read directly from equation (S.7)
50 (equation 2 in the main text).

51 S2 Tracking same-type replicator pairs

52 Above we did not track XX or YY pairs. This means that the above model
53 holds in systems where the replicators do not form self-self complexes. We
54 also conjectured that the results would approximately hold even if they do form
55 such complexes, because individuals in XX and YY pairs do not gain byproduct
56 benefits, and therefore have a lower replication rate than when in XY complexes.
57 We checked this by developing a model that explicitly tracks such pairings. This
58 requires two additional equations for the density of XX and YY complexes, for
59 a total of five equations:

$$\begin{aligned}
\frac{d[X]}{dt} &= (((r_X (1 - d) \eta) - \mu_X) [X]) \\
&\quad - (\beta (1 + \zeta c) [X][Y]) \\
&\quad + (((1 + \kappa) (1 - d) r_X \eta) + \mu_Y + (1 - \xi c) \delta) [XY] \\
&\quad - \beta [X][X] \\
&\quad + (\mu_X + \delta + r_X (1 - d) \eta) [XX]
\end{aligned} \tag{S.8}$$

$$\begin{aligned}
\frac{d[Y]}{dt} &= (((r_Y (1 - c) \eta) - \mu_Y) [Y]) \\
&\quad - (\beta (1 + \zeta c) [Y][X]) \\
&\quad + (((1 + \kappa) r_Y (1 - c) (1 + \omega d) \eta) + \mu_X + (1 - \xi c) \delta) [XY] \\
&\quad - \beta [Y][Y] \\
&\quad + (\mu_Y + \delta + r_Y (1 - d) \eta) [YY]
\end{aligned} \tag{S.9}$$

$$\begin{aligned}
\frac{d[XY]}{dt} &= \beta (1 + \zeta c) [Y][X] \\
&\quad - (\mu_Y + \mu_X + (1 - \xi c) \delta - ((1 + \lambda d) (1 + \alpha c)) r_{XY} (1 - k ([T]))) [XY]
\end{aligned}$$

$$\frac{d[XX]}{dt} = \beta [X][X] - (\mu_X + \mu_Y + \delta - r_{XX} \eta) [XX]$$

$$\frac{d[YY]}{dt} = \beta [Y][Y] - (\mu_Y + \mu_X + \delta - r_{YY} \eta) [YY]$$

60 Where $\eta = 1 - k([X] + [XY] + [Y] + [XX] + [YY])$.

61 Following the same approach as above, we derive the condition for a mutant
62 in replicator type i to spread as:

$$\frac{[\bar{i}]\beta}{[\bar{i}]\beta + [\bar{j}]\beta'} \left(\frac{P'_{ii}}{M'_{ii}} \right) + \frac{[\bar{j}]\beta'}{[\bar{i}]\beta + [\bar{j}]\beta'} \left(\frac{P'_i}{M'_{ij}} + \frac{F'_i}{[\bar{j}]\beta'} \right) > 1 \tag{S.10}$$

63 The new terms, P'_{ii} and M'_{ii} , capture the production and loss of same type
64 pairs, respectively. This inequality is of a similar form to Equation (S.7). The
65 original expression for fitness is now weighted by the relative rate of pairing
66 with the other type. The new component of fitness (the first term) the ratio of
67 production of same type pairs to loss of same type pairs, and is weighted by the
68 relative rate of pairing with the same type.

69 Numerically solving across parameter state space shows that the same re-
70 sults hold as above, with cooperative enzymatic activity failing to spread on
71 its own, association evolving in the absence of such activity, and the two traits
72 co-evolving to higher values than when on their own (Figure S1).

73 S3 An explicit model of pairing

74 The above model left unspecified how cooperation and association increase pair-
75 ing of replicator copies, capturing the effect in the term ρ_{ij} . We now adapt the

76 model to a specific population structure, in order to make this effect explicit.
 77 Doing so necessarily requires sacrificing some of the generality of the first model,
 78 but what it loses in generality it gains in precision.

79 We now need to track two additional populations: X 's and Y 's that have
 80 been produced from pairs. This is because in order to explicitly model the effects
 81 of cooperation and association on pairing, we need to track the densities of copies
 82 produced from pairs before they become randomly mixed in the population.

83 The assumptions are the same as above, except now we allow for some base-
 84 line rate, χ , at which copies produced from pairs immediately pair again. Oth-
 85 erwise they return to the independent populations of X and Y . We assume that
 86 the rate of pairing is increased by both cooperation and physical association, by
 87 a factor $(1 + \lambda d') (1 + \alpha c')$, and is a function of the densities of copies produced,
 88 denoted $[X_o]$ and $[Y_o]$. The new system of equations describing the population
 89 dynamics is now:

$$\begin{aligned}
 \frac{d[X]}{dt} &= (((r_X (1 - d) \eta) - \mu_X) [X]) \\
 &\quad - (\beta (1 + \zeta c) [X][Y]) + \psi [X_o] \\
 \frac{d[Y]}{dt} &= (((r_Y (1 - c) \eta) - \mu_Y) [Y]) \\
 &\quad - (\beta (1 + \zeta c) [Y][X]) + \psi [Y_o] \\
 \frac{d[XY]}{dt} &= \beta (1 + \zeta c) [Y][X] \\
 &\quad - (\mu_Y + \mu_b + (1 - \xi c) \delta) [XY] + (1 + \lambda d) (1 + \alpha c') [X_o][Y_o] \\
 \frac{d[X_o]}{dt} &= ((1 + \kappa) (1 - d) r_X \eta) [XY] - (1 + \lambda d) (1 + \alpha c') [X_o][Y_o] - \psi [X_o] \\
 \frac{d[Y_o]}{dt} &= ((1 + \kappa) r_Y (1 - c) (1 + \omega d) \eta) [XY] \\
 &\quad - (1 + \lambda d) (1 + \alpha c') [X_o][Y_o] - \psi [Y_o], \tag{S.11}
 \end{aligned}$$

90 where $\eta = 1 - k([X] + [XY] + [Y] + [X_o] + [Y_o])$. The parameter ψ controls
 91 the relative rate at which copies produced from pairs return to the population
 92 of free X and Y .

93 Following the same approach as before, we can write system S.11 in matrix
 94 form as:

$$\frac{d}{dt} \begin{bmatrix} [i'] \\ [i'j] \\ [i'_o] \end{bmatrix} = \begin{bmatrix} F'_i - \beta' \overline{[j]} & P'_i & \psi \\ \beta' \overline{[j]} & -M'_{ij} & A'_i \overline{[j_o]} \\ 0 & PR'_i & -A'_i \overline{[j_o]} - \psi \end{bmatrix} \begin{bmatrix} [i'] \\ [i'j] \\ [i'_o] \end{bmatrix} \tag{S.12}$$

95 $P'i$ now measures only replicators returned to the independent population
 96 from complexes as a result of dissociation and destruction, because copies pro-
 97 duced from complexes are captured in the term PR'_i . A'_i measures the associ-
 98 ation of copies produced from complexes, and $\overline{[j_o]}$ is the equilibrium frequency
 99 of copies produced from complexes.

100 Using the next generation theorem (Hurford et al., 2009), we find the con-
 101 dition for a mutant to invade a resident population to be:

$$\frac{\psi P'_i + [\overline{j_o}] P'_i A'_i + \psi P R'_i}{\psi M'_{ij} + [\overline{j_o}] M'_{ij} A'_i - [\overline{j_o}] P R'_i A'_i} + \frac{F'_i}{\beta' [\overline{j}]} > 1 \quad (\text{S.13})$$

102 This equation and its derivatives with respect to changes in c' and d' allow us
 103 to analyse evolution of cooperation or physical association on their own, or their
 104 co-evolution. We recover the result that co-evolution can favour the evolution
 105 of cooperation in conditions under which it would not have evolved on its own
 106 (Figure S2). The result depends crucially on the relative rate at which copies
 107 produced from pairs return to the independent populations (ψ), with $\psi \approx 1$
 108 recovering the main results.

109 S4 Relation to previous mathematical models

110 Adaptive dynamics was developed through a series of papers in the 1990s
 111 (Metz et al., 1992; Rand et al., 1994; Geritz et al., 1997; Dieckmann and Law,
 112 1996). The key assumption is that the mutant is initially rare enough that you
 113 can assume it does not impact the ecological equilibria. Accordingly you can
 114 assume that the resident populations have reached equilibrium when the mutant
 115 is introduced, and study its growth rate in that setting.

116 Law and Dieckmann (1998) developed a model to study the coevolution
 117 of two species in the context of an exploiter-victim relationship evolving into
 118 a vertically transmitted symbiosis. They used the same approach of tracking
 119 both independent populations as well as complexes (in their case ‘holobiont’).
 120 Their main result was that, when costs of being free-living are high enough,
 121 even strictly exploitative relationships can evolve into symbioses in the presence
 122 of vertical transmission. This is analogous to our result that, when benefits
 123 of being in a complex are high enough, stickiness can favour the evolution of
 124 cooperation.

125 Van Baalen and Jansen (2001) extended the work of Law and Dieckmann
 126 (1998) in developing a model to study two-species systems, in which they tracked
 127 the two independent populations as well as complexes. Their goal was to de-
 128 velop a general methodology for studying two interacting populations, and they
 129 specifically discussed two prey populations which shared defence of a predator
 130 and a host parasite interaction which shared a resource. Their key result was
 131 that the invasion condition for a mutant in such interacting populations could
 132 be captured in simple, biologically interpretable expressions (analogous to our
 133 equation 2).

134 Day et al. (2007) developed a similar model for studying two interacting
 135 populations, applying it to the specific case of a mutualism between corals and
 136 zooxanthellae. Their model also allowed explicit tracking of gene frequencies in
 137 both populations.

138 We adopted Van Baalen and Jansen (2001)'s general approach and notation,
 139 but developed a biological model for simple replicators. We studied the case of
 140 one population acting as a cooperators and the other acting to affect association
 141 and dissociation rates. We argue that this is relevant to molecular replicators,
 142 but it is also of potential interest to models of interacting populations in gen-
 143 eral: because when the association rates can evolve, this will affect evolutionary
 144 dynamics.

145 We used an approach developed by Hurford et al. (2009) to derive the inva-
 146 sion conditions. This is why our invasion condition takes a different form than
 147 Van Baalen and Jansen (2001); we found that the Next Generation Theorem al-
 148 lowed us to pull out terms defining the invasion condition that were more easily
 149 interpretable from a biological standpoint in this context.

150 We also extended Van Baalen and Jansen (2001)'s approach in the appendix
 151 by: (i) tracking same-type pairs, and therefore allowing for interactions within
 152 populations (Section S2), and (ii) explicitly tracking the offspring of complexes,
 153 allowing these subpopulations to have distinct dynamics from the larger popu-
 154 lation (Section S3).

Table S1: Summary of key notation

Notation	Definition
$[X]$	Density of replicator type X
$[Y]$	Density of replicator type Y
$[XY]$	Density of replicator pairs
ρ_i	Total production of type i replicators on their own
θ_i	Total production of type i replicators from pairs
r_i	Baseline replication rate of type i replicator
μ_i	Rate of destruction of type i replicators
β	Baseline association rate
δ	Baseline dissociation rate
k	Degree of density dependence
T	Total density of replicators in system
η	Density dependent replication, $= 1 - k[T]$
r_{ij}	Baseline rate at which ij pairs immediately pair again
κ	Byproduct benefit to being in pair
c	Degree of association trait
d	Degree of cooperative enzymatic activity trait
ζ	Increase in association rate due to association mutation
ξ	Decrease in dissociation rate due to association mutation
ω	Increase in replication rate of type Y due to cooperative enzymatic mutation
λ	Increase in the rate pairs re-pair due to cooperative enzymatic mutation
α	Increase in the rate pairs re-pair due to association mutation

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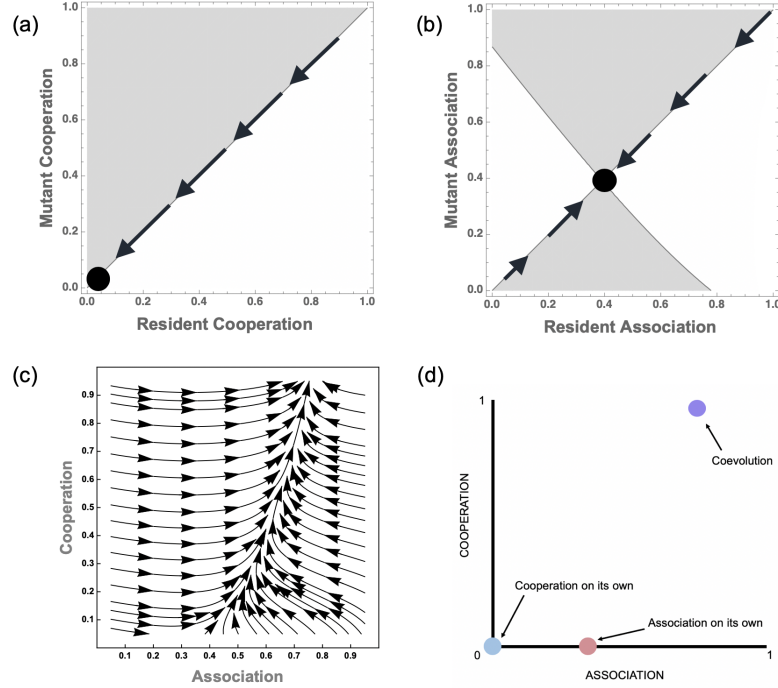


Figure S1: The coevolution of enzymatic activity and association when allowing for same-type pairs to form. Grey shaded areas show regions of state space where selection is negative, and white areas where selection is positive. Arrows depict the direction of evolution in state space along neutral lines. Evolutionarily stable strategies are depicted by solid circles. (a) The evolution of enzymatic activity in X is not favoured. In the absence of association, cooperative enzymatic activity cannot evolve. (b) The evolution of association in Y. In the absence of cooperative enzymatic activity in X, some intermediate level of association in Y is favoured. (c) The coevolution of cooperative enzymatic activity and association. Arrows depict the direction of selection in both traits at a given point in state space. When traits are allowed to coevolve, cooperative enzymatic activity and association both evolve from anywhere in state space, with association reaching higher values than in (b), and enzymatic activity evolving towards its maximal value of 1. (d) A schematic of (a)-(c). Solid circles depict the evolutionarily stable resting point of both populations depending on whether each population evolves independently or evolve jointly. Coevolution favours higher values in both traits. Values for parameters in (a)-(d) are: $\alpha = 20, \lambda = 20, \zeta = 5, \xi = 1, \omega = 20, r_Y = 2.3, r_X = 2.1, r_{XY} = 0.9, r_{XX} = 0.01, r_{YY} = 0.01, k = 0.01, \mu_Y = 1.1, \mu_X = 1.1, \kappa = 100, \beta = 0.01, \delta = 0.9$. All figures generated graphically from the equations described in the Supplementary Material using Mathematica Software version 11.3.0.0.

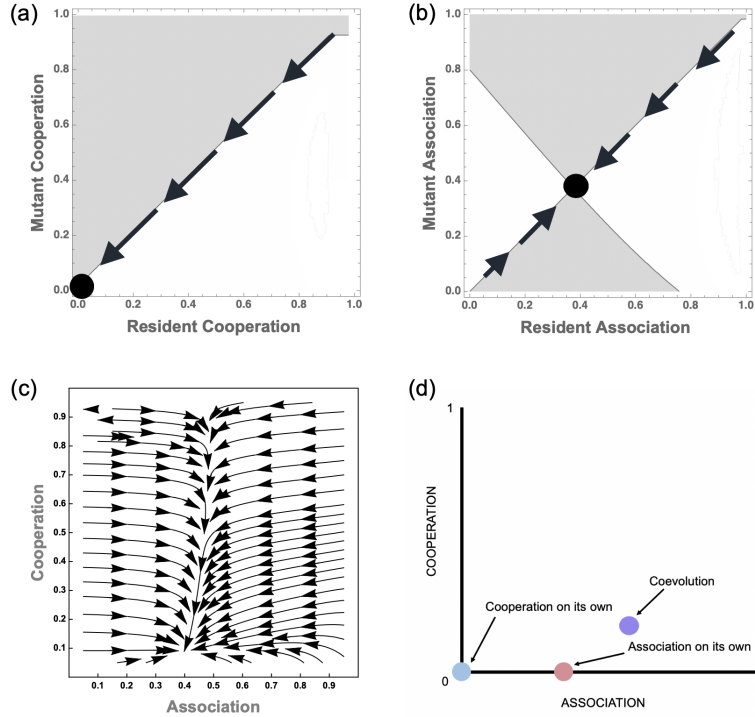


Figure S2: The coevolution of enzymatic activity and association in an explicit model of pairing. Grey shaded areas show regions of state space where selection is negative, and white areas where selection is positive. Arrows depict the direction of evolution in state space along neutral lines. Evolutionarily stable strategies are depicted by solid circles. (a) The evolution of enzymatic activity in X is not favoured. In the absence of association, cooperative enzymatic activity cannot evolve. (b) The evolution of association in Y. In the absence of cooperative enzymatic activity in X, some intermediate level of association in Y is favoured. (c) The coevolution of cooperative enzymatic activity and association. Arrows depict the direction of selection in both traits at a given point in state space. When traits are allowed to coevolve, cooperative enzymatic activity and association both evolve from anywhere in state space, with both traits reaching higher values than in (b) and (c). (d) A schematic of (a)-(c). Solid circles depict the evolutionarily stable resting point of both populations depending on whether each population evolves independently or evolve jointly. Coevolution favours higher values in both traits. Values for parameters in (a)-(d) are: $\alpha = 20, \lambda = 20, \zeta = 5, \xi = 1, \omega = 20, r_Y = 2.3, r_X = 2.1, r_{XY} = 0.9, k = 0.01, \mu_Y = 1.1, \mu_X = 1.1, \kappa = 100, \beta = 0.01, \delta = 0.9, \psi = 1$. All figures generated graphically from the equations described in the Supplementary Material using Mathematica Software version 11.3.0.0.